# Approximation of the Inverse Frame Operator and Applications to Gabor Frames 

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#### Abstract

A frame allows every element in a Hilbert space $\mathscr{H}$ to be written as a linear combination of the frame elements, with coefficients called frame coefficients. Calculation of the frame coefficients requires inversion of an operator $S$ on $\mathscr{H}$. We show how the inverse of $S$ can be approximated as close as we like using finitedimensional linear algebra. In contrast with previous methods, our approximation can be used for any frame. Various consequences for approximation of the frame coefficients or approximation of the solution to a moment problem are discussed. We also apply the results to Gabor frames and frames consisting of translates of a single function. © 2000 Academic Press


## 1. INTRODUCTION

A frame $\left\{f_{i}\right\}_{i=1}^{\infty}$ in a Hilbert space $\mathscr{H}$ has the property that every element $f \in \mathscr{H}$ has a representation as $f=\sum_{i=1}^{\infty} a_{i} f_{i}$ for a set of squaresummable coefficients $\left\{a_{i}\right\}_{i=1}^{\infty}$. Frame theory gives a canonical choice for $\left\{a_{i}\right\}_{i=1}^{\infty}$, the so-called frame coefficients. From the mathematical point of view this is gratifying, but for applications it is a problem that calculation
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of the frame coefficients require inversion of an operator $S$ on $\mathscr{H}$, which is usually infinite-dimensional.

In the present paper we introduce a new method to approximate the inverse of $S$ using finite subsets of the frame. We show that $S^{-1}$ can be approximated using finite-dimensional methods for any frame $\left\{f_{i}\right\}_{i=1}^{\infty}$. This is theoretically interesting, and it also has the potential of being useful in applications. However, the transaction from theory to practice is far from trivial. Comment further on this issue in Section 3.

The present work is strongly motivated by the fact that the projection method discussed in [4] does not allow one to approximate the inverse frame operator corresponding to a Gabor frame. We discuss this important observation in Section 2, along with discussing basic properties of frames.

The new method is presented in Section 3. We show how the inverse frame operator corresponding to any frame can be approximated as close as we want in the strong operator topology, by operators that can be found using only finite-dimensional linear algebra. The speed of convergence is estimated, and some consequences for approximation of the frame coefficients are discussed.

In Section 4 we apply the results to a moment problem. Section 5 is devoted to applications to Gabor frames and frames consisting of translates of a single function.

## 2. PRELIMINARIES

In all that follows, $\mathscr{H}$ denotes a separable Hilbert space with the inner product $\langle\cdot, \cdot\rangle$ linear in the first entry; $I$ denotes a countable index set.

A family of elements $\left\{f_{i}\right\}_{i \in I} \subseteq \mathscr{H}$ is a frame if

$$
\exists A, B>0: \quad A\|f\|^{2} \leqslant \sum_{i \in I}\left|\left\langle f, f_{i}\right\rangle\right|^{2} \leqslant B\|f\|^{2}, \quad \forall f \in \mathscr{H} .
$$

The numbers $A, B$ are called frame bounds.
We say that $\left\{f_{i}\right\}_{i \in I}$ is a Riesz frame if every subfamily of $\left\{f_{i}\right\}_{i \in I}$ is a frame for its closed linear span, with the same frame bounds $A, B$ for each subfamily. Observe, that if $\left\{f_{i}\right\}_{i \in I}$ is known to be a frame, we only need to check the existence of a common lower bound (which is, however, usually the more difficult part).

If $\left\{f_{i}\right\}_{i \in I}$ is a frame, the frame operator is defined by

$$
S: \mathscr{H} \rightarrow \mathscr{H} \quad S f=\sum_{i \in I}\left\langle f, f_{i}\right\rangle f_{i} .
$$

The series defining $S f$ converges unconditionally for all $f \in \mathscr{H}$, and $S$ is a bounded, invertible, and self-adjoint operator. This leads to the frame decomposition:

$$
f=S S^{-1} f=\sum_{i \in I}\left\langle f, S^{-1} f_{i}\right\rangle f_{i}, \quad \forall f \in \mathscr{H}
$$

The possibility of representing every $f \in \mathscr{H}$ in this way is the main feature of a frame. The coefficients $\left\{\left\langle f, S^{-1} f_{i}\right\rangle\right\}_{i \in I}$ are called frame coefficients. For more general information about frames we refer to [9, 12].

Frames can equally well be considered in finite-dimensional spaces. It is easy to see that every finite collection of elements in $\mathscr{H}$ is a frame for its span. For convenience we index our frames by the natural numbers in the rest of the section. Given a frame $\left\{f_{i}\right\}_{i=1}^{\infty}$, we let $n \in N$ and consider the family $\left\{f_{i}\right\}_{i=1}^{n}$, which is a frame for $\mathscr{H}_{n}=\operatorname{span}\left\{f_{i}\right\}_{i=1}^{n}$ with frame operator

$$
S_{n}: \mathscr{H}_{n} \rightarrow \mathscr{H}_{n}, \quad S_{n} f=\sum_{i=1}^{n}\left\langle f, f_{i}\right\rangle f_{i}
$$

and frame decomposition $f=\sum_{i=1}^{n}\left\langle f, S_{n}^{-1} f_{i}\right\rangle f_{i}, f \in \mathscr{H}_{n}$. It can be shown that the orthogonal projection $P_{n}$ of $\mathscr{H}$ onto $\mathscr{H}_{n}$ is given by

$$
P_{n} f=\sum_{i=1}^{n}\left\langle f, S_{n}^{-1} f_{i}\right\rangle f_{i}, \quad f \in \mathscr{H} .
$$

It is very natural to ask whether

$$
\begin{equation*}
\left\langle f, S_{n}^{-1} f_{i}\right\rangle \rightarrow\left\langle f, S^{-1} f_{i}\right\rangle \text { as } n \rightarrow \infty, \quad \forall f \in \mathscr{H}, \quad \forall i \in N \tag{1}
\end{equation*}
$$

Since (1) concerns the limit as $n \rightarrow \infty$, the question makes sense even though $\left\langle f, S_{n}^{-1} f_{i}\right\rangle$ is only defined for $n \geqslant i$.

An affirmative answer to this question may be useful in practical implementations of frames: whereas calculation of $\left\langle f, S^{-1} f_{i}\right\rangle$ requires inversion of $S$ (which can be difficult when $\mathscr{H}$ is infinite-dimensional), calculation of $\left\langle f, S_{n}^{-1} f_{i}\right\rangle$ can be done using finite-dimensional linear algebra.

The question above is studied in [1, 2, 4, 6]. In particular it is shown in [6] that the answer is yes if $\left\{f_{i}\right\}_{i=1}^{\infty}$ is a Riesz frame. Unfortunately, the answer is usually no for a Gabor frame, as we show now. We want to discuss this in some detail. The reader who is mainly interested in a method that works for any frame can skip the rest of the introduction and continue with the next section.

Remember that a Gabor frame for $L^{2}(R)$ has the form

$$
\left\{f_{k, l}(x)\right\}_{k, l \in Z}=\left\{e^{i k b x} f(x-l a)\right\}_{k, l \in Z},
$$

where $a, b>0$ and $f \in L^{2}(R)$ are fixed. Note that $i$ denotes the complex unit number here!

Gabor frames where the function $f$ has compact support play a special role. It is well known, cf. [10], that $\left\{f_{k, l}(x)\right\}_{k, l \in Z}$ is a frame for $L^{2}(R)$ if $f$ has support in an interval of length $2 \pi / b$ and there exist constants $A, B>0$ such that $A \leqslant \sum_{l \in Z}|f(x-l a)|^{2} \leqslant B$, a.e. For a frame $\left\{f_{k, l}(x)\right\}_{k, l \in Z}$ of this type we will now give a quick argument showing that (1) is not satisfied unless $\left\{f_{k, l}(x)\right\}_{k, l \in Z}$ is a Riesz basis.

Proposition 2.1. Suppose that $f \in L^{2}(R)$ has compact support and that $\left\{f_{k, l}(x)\right\}_{k, l \in Z}$ is a frame for $L^{2}(R)$. If (1) is satisfied for an indexing $\left\{f_{i}\right\}_{i=1}^{\infty}$ of the frame elements, then $\left\{f_{k, l}(x)\right\}_{k, l \in Z}$ is a Riesz basis.

Recently, Heil et al. [11] showed that the functions $\left\{f_{k, l}(x)\right\}_{k, l \in Z}$ are linearly independent (meaning that every finite collection of the elements $\left\{f_{k, l}(x)\right\}_{k, l \in Z}$ is linearly independent) if $f \neq 0$ has compact support. Proposition 2.1 now follows from Lemma 2.2 below, which is due to Kim and Lim [13]. For the reader's convenience we include a short new proof:

Lemma 2.2. Let $\left\{f_{i}\right\}_{i=1}^{\infty}$ be a frame and suppose that $\left\{f_{i}\right\}_{i=1}^{\infty}$ is linearly independent. If (1) is satisfied, then $\left\{f_{i}\right\}_{i=1}^{\infty}$ is a Riesz basis.

Proof. Let $n \in N$. The linear independence of $\left\{f_{i}\right\}_{i=1}^{\infty}$ implies that $\left\{f_{i}\right\}_{i=1}^{n}$ is a Riesz basis for $\mathscr{H}_{n}$. The dual basis is $\left\{S_{n}^{-1} f_{i}\right\}_{i=1}^{n}$, so

$$
\left\langle f_{i}, S_{n}^{-1} f_{j}\right\rangle=\delta_{i, j}, \quad i, j=1,2, \ldots, n,
$$

where $\delta_{i, j}=1$ whenever $i=j$, and $\delta_{i, j}=0$ otherwise. By letting $n \rightarrow \infty$ and using (1), we obtain that

$$
\left\langle f_{i}, S^{-1} f_{j}\right\rangle=\delta_{i, j}, \quad \forall i, j \in N,
$$

which means that $\left\{f_{i}\right\}_{i=1}^{\infty}$ is a Riesz basis.
Q.E.D

Remark. In [11], the authors actually conjecture that $\left\{f_{k, l}(x)\right\}_{k, l \in Z}$ is linearly independent whether or not $f$ has compact support. If the conjecture holds, we can remove the assumption about $f$ having compact support from Proposition 2.1. ${ }^{2}$

For a Riesz basis $\left\{f_{i}\right\}_{i=1}^{\infty}$, there exist easier ways to calculate $\left\langle f, S^{-1} f_{i}\right\rangle$ than to use (1), so Proposition 2.1 is a serious shortcoming for Gabor frames. Furthermore, a frame of translates is automatically linearly independent, so the same trouble appears. For wavelets the question is still open.

[^0]In the next section, we introduce a new method for approximation of the inverse frame operator using finite subsets of the frame. In particular we obtain a way of approximation of the frame coefficients which is similar to (1), but which can be used for any frame. We are convinced that the new method will be very useful in many applications where frames appear.

## 3. APPROXIMATION OF $S^{-1}$

In this section we let $\left\{f_{i}\right\}_{i=1}^{\infty}$ be a frame with bounds $A, B$.
Lemma 3.1. Given $n \in N$, there exists a number $m(n)$ such that

$$
\frac{A}{2}\|f\|^{2} \leqslant \sum_{i=1}^{n+m(n)}\left|\left\langle f, f_{i}\right\rangle\right|^{2}, \quad \forall f \in \mathscr{H}_{n} .
$$

Proof. Let $n \in N$. Given $\varepsilon>0$, choose a finite set of elements $g_{k} \in \mathscr{H}_{n}$ such that $\left\|g_{k}\right\|=1, \forall k$, and such that the balls

$$
B\left(g_{k}, \varepsilon\right):=\left\{f \in \mathscr{H}_{n} \mid\left\|f-g_{k}\right\| \leqslant \varepsilon\right\}
$$

cover the compact set $\left\{f \in \mathscr{H}_{n} \mid\|f\|=1\right\}$. Since $A \leqslant \sum_{i=1}^{\infty}\left|\left\langle g_{k}, f_{i}\right\rangle\right|^{2}$ for all $k$, we can choose $m(n)$ such that

$$
A \frac{2}{3} \leqslant \sum_{i=1}^{n+m(n)}\left|\left\langle g_{k}, f_{i}\right\rangle\right|^{2}, \quad \forall k .
$$

Now let $f \in \mathscr{H}_{n},\|f\|=1$. Choose $k$ such that $f \in B\left(g_{k}, \varepsilon\right)$. By the opposite triangle inequality applied to

$$
\left\{\left\langle f, f_{i}\right\rangle\right\}_{i=1}^{n+m(n)}=\left\{\left\langle g_{k}, f_{i}\right\rangle-\left\langle g_{k}-f, f_{i}\right\rangle\right\}_{i=1}^{n+m(n)}
$$

we have

$$
\begin{aligned}
& {\left[\sum_{i=1}^{n+m(n)}\left|\left\langle f, f_{i}\right\rangle\right|^{2}\right]^{1 / 2}} \\
& \quad \geqslant\left[\sum_{i=1}^{n+m(n)}\left|\left\langle g_{k}, f_{i}\right\rangle\right|^{2}\right]^{1 / 2}-\left[\sum_{i=1}^{n+m(n)}\left|\left\langle g_{k}-f, f_{i}\right\rangle\right|^{2}\right]^{1 / 2} \\
& \quad \geqslant \sqrt{A(2 / 3)}-\sqrt{B}\left\|g_{k}-f\right\| \geqslant \sqrt{A(2 / 3)}-\sqrt{B} \varepsilon .
\end{aligned}
$$

By choosing $\varepsilon$ small enough $\sqrt{A(2 / 3)}-\sqrt{B} \varepsilon \geqslant \sqrt{A / 2}$, from which the result follows.
Q.E.D

The next lemma show that for every frame $\left\{f_{i}\right\}_{i=1}^{\infty}$ we can construct a family of frames "approaching $\left\{f_{i}\right\}_{i=1}^{\infty}$," which have common frame bounds. Remember that the approximation (1) works for every Riesz frame; the lemma below turns out to be the key to an improved method that works for every frame.

Lemma 3.2. For any $n \in N$, choose $m(n)$ as in Lemma 3.1. $\left\{P_{n} f_{i}\right\}_{i=1}^{n+m(n)}$ is a frame for $\mathscr{H}_{n}$ with bounds $A / 2, B$. The frame operator is $P_{n} S_{n+m(n)}$ : $\mathscr{H}_{n} \rightarrow \mathscr{H}_{n}$, and

$$
\left\|P_{n} S_{n+m(n)}\right\| \leqslant B,\left\|\left(P_{n} S_{n+m(n)}\right)^{-1}\right\| \leqslant \frac{2}{A} .
$$

Proof. Let $f \in \mathscr{H}_{n}$. Then

$$
\sum_{i=1}^{n+m(n)}\left|\left\langle f, P_{n} f_{i}\right\rangle\right|^{2}=\sum_{i=1}^{n+m(n)}\left|\left\langle f, f_{i}\right\rangle\right|^{2} \geqslant \frac{A}{2}\|f\|^{2} .
$$

Also,

$$
\sum_{i=1}^{n+m(n)}\left|\left\langle f, P_{n} f_{i}\right\rangle\right|^{2}=\sum_{i=1}^{n+m(n)}\left|\left\langle f, f_{i}\right\rangle\right|^{2} \leqslant \sum_{i=1}^{\infty}\left|\left\langle f, f_{i}\right\rangle\right|^{2} \leqslant B\|f\|^{2} .
$$

So $\left\{P_{n} f_{i}\right\}_{i=1}^{n+m(n)}$ is a frame for $\mathscr{H}_{n}$ with the claimed bounds. The frame operator is given by

$$
f \mapsto \sum_{i=1}^{n+m(n)}\left\langle f, P_{n} f_{i}\right\rangle P_{n} f_{i}=P_{n} S_{n+m(n)} f, \quad f \in \mathscr{H}{ }_{n} .
$$

The norm estimates now follow from Proposition 3.4. in [3], where it is proved that the norm of a frame operator is at most equal to the upper frame bound, and that the norm of the inverse frame operator is at most equal to the reciprocal of the lower frame bound.
Q.E.D

We are now ready to prove that $S^{-1}$ can be approximated arbitrarily closely in the strong operator topology using the operators $\left(P_{n} S_{n+m(n)}\right)^{-1} P_{n}$ : $\mathscr{H}_{n} \rightarrow \mathscr{H}_{n}, n \in N$. Observe that $\left(P_{n} S_{n+m(n)}\right)^{-1} P_{n}$ can be found using finitedimensional methods!

Theorem 3.3 Let $\left\{f_{i}\right\}_{i=1}^{\infty}$ be a frame with bounds $A$, B. For $n \in N$, choose $m(n)$ as in Lemma 3.1. Then

$$
\left(P_{n} S_{n+m(n)}\right)^{-1} P_{n} f \rightarrow S^{-1} f \quad \text { for } \quad n \rightarrow \infty, \quad \forall f \in \mathscr{H} .
$$

Proof. Let $f \in \mathscr{H}$ and define

$$
\begin{aligned}
\phi_{n} & :=S^{-1} f-\left(P_{n} S_{n+m(n)}\right)^{-1} P_{n} f \\
& =P_{n} S^{-1} f-\left(P_{n} S_{n+m(n)}\right)^{-1} P_{n} f+\left(I-P_{n}\right) S^{-1} f .
\end{aligned}
$$

Since $\left(I-P_{n}\right) S^{-1} f \rightarrow 0$ as $n \rightarrow \infty$, it is enough to show that

$$
\psi_{n}:=P_{n} S^{-1} f-\left(P_{n} S_{n+m(n)}\right)^{-1} P_{n} f \rightarrow 0 .
$$

Since $\psi_{n} \in \mathscr{H}_{n}$ we can apply the operator $P_{n} S_{n+m(n)}$ to get

$$
\psi_{n}=\left(P_{n} S_{n+m(n)}\right)^{-1}\left(P_{n} S_{n+m(n)} P_{n} S^{-1} f-P_{n} f\right) .
$$

Consequently,

$$
\begin{aligned}
\left\|\psi_{n}\right\| & \leqslant\left\|\left(P_{n} S_{n+m(n)}\right)^{-1}\right\| \cdot\left\|P_{n} S_{n+m(n)} P_{n} S^{-1} f-P_{n} f\right\| \\
& \leqslant \frac{2}{A}\left\|S_{n+m(n)} P_{n} S^{-1} f-f\right\| \rightarrow 0 \quad \text { for } \quad n \rightarrow \infty
\end{aligned}
$$

Q.E.D

The proof of Theorem 3.3 gives an estimate for how fast $\left(P_{n} S_{n+m(n)}\right)^{-1} P_{n} f$ converges to $S^{-1} f$ :

$$
\begin{aligned}
\| S^{-1} f & -\left(P_{n} S_{n+m(n)}\right)^{-1} P_{n} f \| \\
= & \left\|\phi_{n}\right\| \leqslant\left\|\psi_{n}\right\|+\left\|\left(I-P_{n}\right) S^{-1} f\right\| \\
\leqslant & \frac{2}{A}\left(\left\|f-S_{n+m(n)} S^{-1} f\right\|+\left\|S_{n+m(n)}\left(I-P_{n}\right) S^{-1} f\right\|\right) \\
& +\left\|\left(I-P_{n}\right) S^{-1} f\right\| \\
\leqslant & \frac{2}{A}\left\|\sum_{i=n+m(n)+1}^{\infty}\left\langle S^{-1} f, f_{i}\right\rangle f_{i}\right\|+\left(\frac{2 B}{A}+1\right)\left\|\left(I-P_{n}\right) S^{-1} f\right\| \\
\leqslant & \frac{2 \sqrt{B}}{A}\left[\sum_{i=n+m(n)+1}^{\infty}\left|\left\langle S^{-1} f, f_{i}\right\rangle\right|^{2}\right]^{1 / 2}+\left(\frac{2 B}{A}+1\right)\left\|\left(I-P_{n}\right) S^{-1} f\right\| .
\end{aligned}
$$

This is, however, not good for applications since the estimate involves $S^{-1}$. The next theorem shows that we can obtain more useful estimates for the speed of convergence by replacing the condition on $m(n)$ by a stronger one. First, we need a lemma. The proof is very similar to the proof of Lemma 3.1, so we omit it.

Lemma 3.4. Let $\mathscr{H}, \mathscr{L}$ be Hilbert spaces and let $T_{k}: \mathscr{H} \rightarrow \mathscr{L}, k \in N$, be a sequence of bounded operators such that $T_{k} f \rightarrow 0$ for $k \rightarrow \infty, \forall f \in \mathscr{H}$. Given $\varepsilon>0$ and a finite dimensional subspace $\mathscr{K}$ of $\mathscr{H}$, there exists a number $k_{0}$ such that for $k \geqslant k_{0}$,

$$
\left\|T_{k} f\right\| \leqslant \varepsilon\|f\|, \quad \forall f \in \mathscr{K} .
$$

Lemma 3.4 is needed in order to ensure that the hypothesis of the theorem below can be satisfied. Consider a fixed $n \in N$ and let $\mathscr{K}:=\mathscr{H}_{n}$. The family of operators

$$
T_{k}: \mathscr{H} \rightarrow \ell^{2}, \quad T_{k} f=\left\{\left\langle f, f_{i}\right\rangle\right\}_{i=k}^{\infty}
$$

satisfies the condition in Lemma 3.4. Thus, given $\varepsilon>0$, there exists $k_{0} \in N$ such that

$$
\left\|T_{k_{0}} f\right\|^{2} \leqslant \sum_{i=k_{0}}^{\infty}\left|\left\langle f, f_{i}\right\rangle\right|^{2} \leqslant \varepsilon\|f\|^{2}, \quad \forall f \in \mathscr{H}_{n} .
$$

Denote the restriction of an operator $T$ to a subspace $\mathscr{K}$ by $T_{\mid \mathscr{K}}$.
Theorem 3.5. Let $\left\{f_{i}\right\}_{i=1}^{\infty}$ be a frame with bounds $A, B$ and let $\left\{\varepsilon_{n}\right\}_{n=1}^{\infty}$ $\subseteq] 0, A[$ be a decreasing sequence of real numbers converging to 0 . Given $n \in N$, choose $m(n)$ such that

$$
\sum_{i=n+m(n)+1}^{\infty}\left|\left\langle f, f_{i}\right\rangle\right|^{2} \leqslant \frac{\varepsilon_{n}^{2}}{B}\|f\|^{2}, \quad \forall f \in \mathscr{H}_{n} .
$$

Consider $S_{n+m(n)}$ as an isomorphism from $\mathscr{H}_{n}$ onto $\mathscr{K}_{n}:=S_{n+m(n)} \mathscr{H}_{n}$ and let $Q_{n}$ denote the orthogonal projection of $\mathscr{H}$ onto $\mathscr{K}_{n}$. Then

$$
\begin{aligned}
& \| S^{-1} f-\left(S_{\left.n+m(n) \mid \mathscr{H}_{n}\right)^{-1} Q_{n} f \|}\right. \\
& \quad \leqslant \frac{1}{A}\left(\left\|\left(I-Q_{n}\right) f\right\|+\frac{\varepsilon_{n}}{A-\varepsilon_{n}}\left\|Q_{n} f\right\|\right), \quad \forall f \in \mathscr{H} .
\end{aligned}
$$

Proof. By assumption,

$$
\begin{aligned}
\left\|\left(S-S_{n+m(n)}\right)_{\mid \mathscr{H}_{n}}\right\|^{2} & =\sup _{f \in \mathscr{H}_{n},\|f\|=1}\left\|\left(S-S_{n+m(n)}\right) f\right\|^{2} \\
& =\sup _{f \in \mathscr{H}_{n},\|f\|=1}\left\|\sum_{i=n+m(n)+1}^{\infty}\left\langle f, f_{i}\right\rangle f_{i}\right\|^{2} \\
& \leqslant \sup _{f \in \mathscr{H}_{n},\|f\|=1} B \sum_{i=n+m(n)+1}^{\infty}\left|\left\langle f, f_{i}\right\rangle\right|^{2} \leqslant \varepsilon_{n}^{2} .
\end{aligned}
$$

Thus $\left\|\left(S-S_{n+m(n)}\right)_{\mid \mathscr{H}_{n}}\right\| \leqslant \varepsilon_{n}$. It follows that for $f \in \mathscr{H}_{n}$,

$$
\begin{aligned}
\left\|S_{n+m(n)} f\right\| & =\left\|S f-\left(S f-S_{n+m(n)} f\right)\right\| \\
& \geqslant\|S f\|-\left\|\left(S-S_{n+m(n)}\right) f\right\| \geqslant\left(A-\varepsilon_{n}\right)\|f\| .
\end{aligned}
$$

Therefore

$$
\left\|\left(S_{n+m(n) \mid \mathscr{H}_{n}}\right)^{-1}\right\| \leqslant \frac{1}{A-\varepsilon_{n}} .
$$

Now, for $f \in \mathscr{H}$ we have

$$
\begin{aligned}
& \| S^{-1} f-\left(S_{\left.n+m(n) \mid \mathscr{H}_{n}\right)^{-1} Q_{n} f \|} \leqslant\right. \\
& \leqslant\left\|S^{-1} f-S^{-1} Q_{n} f\right\|+\| S^{-1} Q_{n} f-\left(S_{\left.n+m(n) \mid \mathscr{H}_{n}\right)^{-1}} Q_{n} f \|\right. \\
& \leqslant\left\|S^{-1}\left(I-Q_{n}\right) f\right\|+\| S^{-1}\left(I-S\left(S_{\left.\left.n+m(n) \mid \mathscr{H}_{n}\right)^{-1}\right)} Q_{n} f \|\right.\right. \\
& \leqslant \frac{1}{A}\left(\left\|\left(I-Q_{n}\right) f\right\|+\left\|\left(S_{n+m(n)}-S\right)\left(S_{n+m(n) \mid \mathscr{H}_{n}}\right)^{-1} Q_{n} f\right\|\right) \\
& \leqslant \frac{1}{A}\left(\left\|\left(I-Q_{n}\right) f\right\|+\left\|\left(S-S_{n+m(n)}\right)_{\mathscr{H}}\right\|\right. \\
& \times \|\left(S_{\left.\left.n+m(n) \mid \mathscr{H}_{n}\right)^{-1}\|\cdot\| Q_{n} f \|\right)}\right. \\
& \leqslant \frac{1}{A}\left(\left\|\left(I-Q_{n}\right) f\right\|+\frac{\varepsilon_{n}}{A-\varepsilon_{n}}\left\|Q_{n} f\right\|\right) .
\end{aligned}
$$

The condition in Theorem 3.5 implies that for all $f \in \mathscr{H}_{n}$ we have

$$
\sum_{i=1}^{n+m(n)}\left|\left\langle f, f_{i}\right\rangle\right|^{2} \geqslant\left(A-\frac{\varepsilon_{n}^{2}}{B}\right)\|f\|^{2} .
$$

By comparing this to the condition on $m(n)$ in Theorem 3.3, namely

$$
\sum_{i=1}^{n+m(n)}\left|\left\langle f, f_{i}\right\rangle\right|^{2} \geqslant \frac{A}{2}\|f\|^{2}, \quad \forall f \in \mathscr{H}_{n},
$$

we see that as soon as $\varepsilon_{n} \leqslant \sqrt{A B / 2}$, the condition in Theorem 3.5 forces us to choose a larger value for $m(n)$ than in Theorem 3.3. Thus, in the following we will specify carefully which condition we refer to. We will use both
results, partly for the above reason, and partly because the condition in Theorem 3.5 can not be verified using linear algebra as in the case with the condition in Theorem 3.3.

A problem of particular interest is that of approximation of the frame coefficients $\left\langle f, S^{-1} f_{i}\right\rangle, f \in \mathscr{H}$. Theorem 3.3 shows that we can approximate $\left\langle f, S^{-1} f_{i}\right\rangle$ as close as we want using finite-dimensional methods, since

$$
\left\langle f,\left(P_{n} S_{n+m(n)}\right)^{-1} P_{n} f_{i}\right\rangle \rightarrow\left\langle f, S^{-1} f_{i}\right\rangle \quad \text { for } \quad n \rightarrow \infty, \quad \forall f \in \mathscr{H} .
$$

Actually, much more is true: the sequence of coefficients $\left\{\left\langle f,\left(P_{n} S_{n+m(n)}\right)^{-1} P_{n} f_{i}\right\rangle\right\}_{i=1}^{n+m(n)}$ converges to $\left\{\left\langle f, S^{-1} f_{i}\right\rangle\right\}_{i=1}^{\infty}$ in $\ell^{2}$-sense as $n \rightarrow \infty$; i.e.,

$$
\begin{aligned}
& \sum_{i=1}^{n+m(n)}\left|\left\langle f,\left(P_{n} S_{n+m(n)}\right)^{-1} P_{n} f_{i}\right\rangle-\left\langle f, S^{-1} f_{i}\right\rangle\right|^{2} \\
& \quad+\sum_{i=n+m(n)+1}^{\infty}\left|\left\langle f, S^{-1} f_{i}\right\rangle\right|^{2} \rightarrow 0 \quad \text { for } \quad n \rightarrow \infty
\end{aligned}
$$

This is the content of the following theorem. Observe that the second term above trivially converges to 0 as $n \rightarrow \infty$, so we can concentrate on the first term.

Theorem 3.6. For $n \in N$, choose $m(n)$ as in Lemma 3.1. Then

$$
\begin{aligned}
& \sum_{i=1}^{n+m(n)}\left|\left\langle f,\left(P_{n} S_{n+m(n)}\right)^{-1} P_{n} f_{i}\right\rangle-\left\langle f, S^{-1} f_{i}\right\rangle\right|^{2} \rightarrow 0 \\
& \quad \text { for } n \rightarrow \infty, \quad \forall f \in \mathscr{H} .
\end{aligned}
$$

Proof.

$$
\begin{aligned}
& \sum_{i=1}^{n+m(n)}\left|\left\langle f,\left(P_{n} S_{n+m(n)}\right){ }^{-1} P_{n} f_{i}\right\rangle-\left\langle f, S^{-1} f_{i}\right\rangle\right|^{2} \\
& \quad=\sum_{i=1}^{n+m(n)}\left|\left\langle\left(P_{n} S_{n+m(n)}\right)^{-1} P_{n} f-S^{-1} f, f_{i}\right\rangle\right|^{2} \\
& \quad \leqslant B\left\|S^{-1} f-\left(P_{n} S_{n+m(n)}\right)^{-1} P_{n} f\right\|^{2} \rightarrow 0 \quad \text { for } \quad n \rightarrow \infty .
\end{aligned}
$$

A similar proof shows that under the assumption in Theorem 3.5, also

$$
\begin{aligned}
& \sum_{i=1}^{n+m(n)} \mid\left\langle f,\left(S_{\left.n+m(n) \mid \mathscr{H}_{n}\right)^{-1}} Q_{n} f_{i}\right\rangle-\left.\left\langle f, S^{-1} f_{i}\right\rangle\right|^{2} \rightarrow 0\right. \\
& \quad \text { for } n \rightarrow \infty, \quad \forall f \in \mathscr{H} .
\end{aligned}
$$

The fact that the inverse frame operator and the frame coefficients can be approximated arbitrarily closely does not make it a trivial matter to use the results in concrete applications. For large values of $n$, the dimension of $\mathscr{H}_{n}$ is correspondingly large, making it computationally expensive to compute $\left(P_{n} S_{n+m(n)}\right)^{-1}$. Application of our result is simplified drastically in cases where $S_{n}$ has a special structure that makes the inversion easy. Recently it has been discovered [14] that the frame operator $S$ for a finite discrete Gabor expansion (i.e., Gabor analysis on a finite subset of $\ell^{2}(Z)$ ) has rich mathematical structure which reduces the computational cost in inverting $S$. In [14] Theorem 8.4.3 Strohmer estimates the number of operations needed. Thus our result has a great potential for application in that case. For a different approach to this special case we refer to [15].

It is not known whether the frame operator for a finite Gabor system in $L^{2}(R)$ also has a structure that makes inversion easier. This is an interesting open question for future work.

## 4. APPROXIMATION OF THE SOLUTION TO A MOMENT PROBLEM

The principle of approximation using finite subsets of the frame can be used in many other contexts, of which we present one here. Let again $\left\{f_{i}\right\}_{i=1}^{\infty}$ be a frame for $\mathscr{H}$ and let $\left\{a_{i}\right\}_{i=1}^{\infty} \in \ell^{2}(N)$. We ask whether there exists $f \in \mathscr{H}$ such that

$$
\left\langle f, f_{i}\right\rangle=a_{i}, \quad \forall i \in N .
$$

A problem of this type is called a moment problem. For the general theory we refer to [16]. It is easy to find example where there is no solution (this is for instance the case if there is a linear dependence between some elements in $\left\{f_{i}\right\}_{i=1}^{\infty}$ that is not reflected in $\left\{a_{i}\right\}_{i=1}^{\infty}$ ) but as shown in [5] there always exists a unique element in $\mathscr{H}$ minimizing $\sum_{i=1}^{\infty}\left|a_{i}-\left\langle f, f_{i}\right\rangle\right|^{2}$; this element is $f=\sum_{i=1}^{\infty} a_{i} S^{-1} f_{i}$. We call $f=\sum_{i=1}^{\infty} a_{i} S^{-1} f_{i}$ the best approximation solution to the moment problem.

In light of Theorem 3.3, a natural question is whether

$$
\sum_{i=1}^{n+m(n)} a_{i}\left(P_{n} S_{n+m(n)}\right)^{-1} P_{n} f_{i} \rightarrow \sum_{i=1}^{\infty} a_{i} S^{-1} f_{i}, \quad \forall\left\{a_{j}\right\}_{i=1}^{\infty} \in \ell^{2}(N) .
$$

The next theorem shows that the answer is yes. Again, this means that the best approximation solution to the moment problem can be approximated as close as we want using finite-dimensional methods.

Theorem 4.1. For $n \in N$, choose $m(n)$ as in Lemma 3.1. Then

$$
\begin{aligned}
& \sum_{i=1}^{n+m(n)} a_{i}\left(P_{n} S_{n+m(n)}\right)^{-1} P_{n} f_{i} \rightarrow \sum_{i=1}^{\infty} a_{i} S^{-1} f_{i} \\
& \quad \text { for } n \rightarrow \infty, \quad \forall\left\{a_{i}\right\}_{i=1}^{\infty} \in \ell^{2}(N) .
\end{aligned}
$$

Proof. Let $\left\{a_{i}\right\}_{i=1}^{\infty} \in \ell^{2}(N)$. By Theorem 3.3 applied to $\sum_{i=1}^{\infty} a_{i} f_{i}$,

$$
\begin{gathered}
\left(P_{n} S_{n+m(n)}\right)^{-1} P_{n} \sum_{i=1}^{\infty} a_{i} f_{i} \rightarrow S^{-1} \sum_{i=1}^{\infty} a_{i} f_{i} \\
=\sum_{i=1}^{\infty} a_{i} S^{-1} f_{i} \quad \text { for } n \rightarrow \infty .
\end{gathered}
$$

Since

$$
\begin{aligned}
\left(P_{n} S_{n+m(n)}\right)^{-1} P_{n} \sum_{i=1}^{\infty} a_{i} f_{i}= & \sum_{i=1}^{n+m(n)} a_{i}\left(P_{n} S_{n+m(n)}\right)^{-1} P_{n} f_{i} \\
& +\sum_{i=n+m(n)+1}^{\infty} a_{i}\left(P_{n} S_{n+m(n)}\right)^{-1} P_{n} f_{i},
\end{aligned}
$$

it is enough to show that

$$
\sum_{i=n+m(n)+1}^{\infty} a_{i}\left(P_{n} S_{n+m(n)}\right)^{-1} P_{n} f_{i} \rightarrow 0 \quad \text { for } \quad n \rightarrow \infty .
$$

But this can be showed using the following sequence of estimates:

$$
\begin{aligned}
& \left\|\quad \sum_{i=n+m(n)+1}^{\infty} a_{i}\left(P_{n} S_{n+m(n)}\right)^{-1} P_{n} f_{i}\right\|^{2} \\
& \quad=\sup _{\|f\|=1}\left|\left\langle\sum_{i=n+m(n)+1}^{\infty} a_{i}\left(P_{n} S_{n+m(n)}\right)^{-1} P_{n} f_{i}, f\right\rangle\right|^{2} \\
& \quad=\sup _{\|f\|=1}\left|\sum_{i=n+m(n)+1}^{\infty} a_{i}\left\langle\left(P_{n} S_{n+m(n)}\right)^{-1} P_{n} f_{i}, f\right\rangle\right|^{2}
\end{aligned}
$$

$$
\begin{aligned}
& \leqslant \sum_{i=n+m(n)+1}^{\infty}\left|a_{i}\right|^{2} \cdot \sup _{\|f\|=1} \sum_{i=n+m(n)+1}^{\infty}\left|\left\langle\left(P_{n} S_{n+m(n)}\right)^{-1} P_{n} f_{i}, f\right\rangle\right|^{2} \\
& \leqslant \sum_{i=n+m(n)+1}^{\infty}\left|a_{i}\right|^{2} \cdot \sup _{\|f\|=1}^{\infty} \sum_{i=1}^{\infty}\left|\left\langle f_{i},\left(P_{n} S_{n+m(n)}\right)^{-1} P_{n} f\right\rangle\right|^{2} \\
& \leqslant B \sum_{i=n+m(n)+1}^{\infty}\left|a_{i}\right|^{2} \cdot \sup _{\|f\|=1}\left\|\left(P_{n} S_{n+m(n)}\right)^{-1} P_{n} f\right\|^{2} \\
& \leqslant \frac{4 B}{A^{2}} \cdot \sum_{i=n+m(n)+1}^{\infty}\left|a_{i}\right|^{2} \rightarrow 0 \quad \text { for } n \rightarrow \infty ;
\end{aligned}
$$

here the last estimate is a consequence of $\left\|\left(P_{n} S_{n+m(n)}\right)^{-1}\right\| \leqslant 2 / A$. $\quad$ Q.E.D
We have the following estimate for the speed of convergence:

$$
\begin{aligned}
& \left\|\sum_{i=1}^{\infty} a_{i} S^{-1} f_{i}-\sum_{i=1}^{n+m(n)} a_{i}\left(P_{n} S_{n+m(n)}\right)^{-1} P_{n} f_{i}\right\| \\
& \leqslant\left\|\sum_{i=1}^{\infty} a_{i} S^{-1} f_{i}-\sum_{i=1}^{\infty} a_{i}\left(P_{n} S_{n+m(n)}\right)^{-1} P_{n} f_{i}\right\| \\
& \quad+\left\|\sum_{i=n+m(n)+1}^{\infty} a_{i}\left(P_{n} S_{n+m(n)}\right)^{-1} P_{n} f_{i}\right\| \\
& \leqslant
\end{aligned}
$$

Using the condition from Theorem 3.5 we obtain a result similar to Theorem 4.1 and a corresponding estimate of the speed of convergence. We state the result without proof.

Theorem 4.2. Let $\varepsilon_{n}, m(n)$ and $Q_{n}$ be as in Theorem 3.5. Then for all sequences $\left\{a_{i}\right\}_{i=1}^{\infty} \in \ell^{2}(N)$ we have that

$$
\begin{aligned}
& \left\|\sum_{i=1}^{\infty} a_{i} S^{-1} f_{i}-\sum_{i=1}^{n+m(n)} a_{i}\left(S_{n+m(n) \mid \mathscr{\varkappa}_{i}}\right)^{-1} Q_{n} f_{i}\right\| \\
& \quad \leqslant \frac{1}{A}\left(\left\|\left(I-Q_{n}\right) f\right\|+\frac{\varepsilon_{n}}{A-\varepsilon_{n}}\left\|Q_{n} f\right\|\right)+\frac{1}{A-\varepsilon_{n}} \sqrt{B} \sum_{i=n+m(n)+1}^{\infty}\left|a_{i}\right|^{2} .
\end{aligned}
$$

## 5. EXAMPLES

For notational convenience we indexed the frames by the natural numbers in the previous sections. It is clear that the same results can be formulated for any countable index set $I$. When $\left\{f_{i}\right\}_{i \in I}$ is a frame and $J \subseteq I$ is finite, denote the frame operator for $\left\{f_{i}\right\}_{i \in J}$ by $S_{J}$. Let $\mathscr{H}_{j}:=\operatorname{span}\left\{f_{i}\right\}_{i \in J}$ and let $P_{J}$ be the orthogonal projection onto $\mathscr{H}_{J}$.

Let $\left\{I_{n}\right\}_{n=1}^{\infty}$ be a collection of finite subsets of $I$ such that

$$
I_{1} \subseteq I_{2} \subseteq \cdots \subseteq I_{n} \cdots \nearrow I .
$$

With this notation Theorem 3.5 can be formulated in the following way: Given $n \in N$, choose a finite set $J_{n}$ containing $I_{n}$ such that

$$
\begin{equation*}
\sum_{i \neq J_{n}}\left|\left\langle f, f_{i}\right\rangle\right|^{2} \leqslant \frac{\varepsilon_{n}^{2}}{B}\|f\|^{2}, \quad \forall f \in \mathscr{H}_{n} . \tag{2}
\end{equation*}
$$

Let $Q_{I_{n}}$ denote the orthogonal projection of $L^{2}(R)$ onto $\mathscr{K}_{I_{n}}:=S_{J_{n}} \mathscr{H}_{I_{n}}$. Then

$$
\begin{aligned}
& \left\|S^{-1} f-\left(S_{J_{n} \mid \mathscr{I}_{I_{n}}}\right)^{-1} Q_{I_{n}} f\right\| \\
& \quad \leqslant \frac{1}{A}\left(\left\|\left(I-Q_{I_{n}}\right) f\right\|+\frac{\varepsilon_{n}}{A-\varepsilon_{n}}\left\|Q_{I_{n}} f\right\|\right), \quad \forall f \in \mathscr{H} .
\end{aligned}
$$

In the present section we are mainly interested in how to find $J_{n}$ in concrete situations. The example we present here involve two types of operators on $L^{2}(R)$, namely

$$
\text { translation } T_{a} \text { with } a \in R:\left(T_{a} f\right)(x)=f(x-a), \quad f \in L^{2}(R), \quad x \in R
$$

and

$$
\text { modulation } E_{b}, b \in R:\left(E_{b} f\right)(x)=e^{i b x} f(x), \quad f \in L^{2}(R), \quad x \in R .
$$

Theorem 5.1. Let $f \in L^{2}(R)$ have compact support and let $\left\{a_{i}\right\}_{i=-\infty}^{\infty}$ be an increasing sequence of real numbers. Suppose that $\left\{f_{i}\right\}_{i=-\infty}^{\infty}:=\left\{T_{a_{i}} f\right\}_{i=-\infty}^{\infty}$ is a frame for $\mathscr{H}:=\overline{\operatorname{span}}\left\{f_{i}\right\}_{i=-\infty}^{\infty}$. Define $I_{n}:=\{-n,-n+1, \ldots, 0,1, \ldots, n\}$. Then there exists a nonnegative integer $m$ independent of $n$ such that

$$
\left\|S^{-1} f-\left(S_{I_{n+m} \mid \mathscr{H}_{n}}\right)^{-1} Q_{I_{n}} f\right\| \leqslant \frac{1}{A}\left\|f-Q_{I_{n}} f\right\|, \quad \forall f \in \mathscr{H} .
$$

Proof. By [8], the assumption that $\left\{f_{i}\right\}_{i=-\infty}^{\infty}$ is a frame for $\mathscr{H}$ implies that $\left\{a_{i}\right\}_{i=-\infty}^{\infty}$ is uniformly relatively separated. That is, there exists a finite collection of disjoint index sets $J_{k}, k=1, \ldots, l$, such that $Z=\bigcup_{k=1}^{l} J_{k}$ and each set $\left\{a_{i}\right\}_{i \in J_{k}}$ is $\delta_{k}$-separated, meaning that

$$
\delta_{k}:=\min _{i, j \in J_{k}, i \neq j}\left|a_{i}-a_{j}\right|>0 .
$$

Now, chose $\delta \in] 0, \min \delta_{j}[$. Observe that any interval of length $\delta$ contains at most $l$ points $a_{i}, i \in Z$.

By assumption, $f$ has compact support, say, $\operatorname{supp}(f) \subseteq[c, d]$. So for $a \in R, \operatorname{supp}\left(T_{a} f\right) \subseteq[a+c, a+d]$. Consequently, if $g \in \mathscr{H}_{I_{n}}$, then $\operatorname{supp}(g) \subseteq$ $\left[a_{-n}+c, a_{n}+d\right]$. It follows that $\left\langle g, T_{a} f\right\rangle=0$ for all $g \in \mathscr{H}_{I_{n}}$ if

$$
a+c \geqslant a_{n}+d \quad \text { or } \quad a+d \leqslant a_{-n}+c,
$$

i.e., if

$$
a-a_{n} \geqslant d-c \quad \text { or } \quad a_{-n}-a \geqslant d-c .
$$

Let $[a$ ] denote the integer part of the number $a \in R$. An interval of length $d-c$ contains at most $[(d-c) / \delta]+1$ points from each separated sequences $\left\{a_{i}\right\}_{i \in J_{k}}$, and thus at most $m:=l([(d-c) / \delta]+1)$ points from $\left\{a_{i}\right\}_{i=-\infty}^{\infty}$. Thus

$$
\sum_{i \notin I_{n+m}}\left|\left\langle g, f_{i}\right\rangle\right|^{2}=0 \quad \forall g \in \mathscr{H}_{I_{n}},
$$

and now the result follows from the version of Theorem 3.5 that we stated at the beginning of the section.
Q.E.D

Note that, according to [8], a collection of translates of a single function can not form a frame for $L^{2}(R)$, so in the theorem above $\mathscr{H}$ is a proper subspace of $L^{2}(R)$.

Define the Fourier transformation of $f \in L^{1}(R)$ by

$$
\hat{f}(y)=\frac{1}{2 \pi} \int f(x) e^{i x y} d x
$$

Note, that $i$ denotes the complex unit number here! As usual we extend the Fourier transformation to an isometry from $L^{2}(R)$ onto $L^{2}(R)$.

Our next application of the theorems in Section 3 concerns Gabor frames $\left\{f_{k, l}(x)\right\}_{k, l \in Z}$, as defined in Section 2. Observe that in terms of the translation and modulation operators we have $f_{k, l}(x)=\left(E_{k b} T_{l a} f\right)(x)$.

Our approach is strongly motivated by Daubechies' celebrated paper [10]. For $M \in N$, define two operators $Q_{M}, R_{M}$ on $L^{2}(R)$ by

$$
\left(Q_{M} g\right)(x)=\mathbf{1}_{[-M ; M]}(x) g(x) \quad \text { and } \quad\left(R_{M} g\right)^{\wedge}(x)=\mathbf{1}_{[-M ; M]}(x) \hat{g}(x)
$$

On p. 1001 in [10] Daubechies shows that under certain regularity conditions of $f \in L^{2}(R)$ (see the exact requirements in Theorem 5.2 below), there exists a constant $k(a, b)$ (as the notation indicates, depending only on the values of $a, b$, which are fixed here) such that for all $M, m \in N$,

$$
\sum_{|k b| \geqslant M+m, l \in Z}\left|\left\langle Q_{M} g, f_{k, l}\right\rangle\right|^{2} \leqslant k(a, b)\left(1+m^{2}\right)^{-2 \alpha+1}\|g\|^{2}, \quad \forall g \in L^{2}(R) .
$$

The constant $k(a, b)$ is estimated explicitly in [10]. Furthermore, a similar estimate holds with $Q_{M}$ replaced by $R_{M}$ and the roles of $k, l$ switched:

$$
\sum_{||a| \geqslant M+m, k \in Z}\left|\left\langle R_{M} g, f_{k, l}\right\rangle\right|^{2} \leqslant k(b, a)\left(1+m^{2}\right)^{-2 \alpha+1}\|g\|^{2}, \quad \forall g \in L^{2}(R) .
$$

For $n \in N$, we define the finite index set $I_{n}$ by

$$
I_{n}=\{(k, l) \in Z \times Z| | k b|\leqslant n,|l a| \leqslant n\} .
$$

Theorem 5.2. Let $f \in L^{2}(R)$ and assume that for constants $C>0$, $\alpha>1 / 2$ we have

$$
|f(x)| \leqslant C\left(1+x^{2}\right)^{-\alpha}, \forall x \in R \quad \text { and } \quad|\hat{f}(y)| \leqslant C\left(1+y^{2}\right)^{-\alpha}, \quad \forall y \in R
$$

Furthermore, assume that $\left\{f_{k, l}(x)\right\}_{k, l \in Z}$ is a frame for $L^{2}(R)$ with bounds $A, B$ and let $\left\{\varepsilon_{n}\right\}_{n=1}^{\infty}$ be a decreasing sequence of real numbers converging to 0 . Given $n \in N$, choose $M>n$ such that

$$
\left\|\left(I-Q_{M}\right) g\right\| \leqslant \varepsilon_{n}(B(4 B+1))^{-1 / 2}\|g\|, \quad \forall g \in \mathscr{H}_{I_{n}}
$$

and

$$
\left\|\left(I-R_{M}\right) g\right\| \leqslant \varepsilon_{n}(B(4 B+1))^{-1 / 2},\|g\|, \quad \forall g \in \mathscr{H}_{I-n} .
$$

Then, choose $m$ such that

$$
m>\sqrt{\left(\varepsilon_{n}^{2} / B(4 B+1)(k(a, b)+k(b, a))\right)^{1 /(-2 \alpha+1)}-1} .
$$

Then we have:
(i) $\sum_{(k, l) \notin I_{M+m}}\left|\left\langle g, f_{k, l}\right\rangle\right|^{2} \leqslant \frac{\varepsilon_{n}^{2}}{B}\|g\|^{2}, \quad \forall g \in \mathscr{H}_{I_{n}}$
and for all $f \in L^{2}(R)$,
(ii) $\left\|S^{-1} f-\left(S_{I_{M+m} \mid \mathscr{P}_{I n}}\right)^{-1} Q_{I_{n}} f\right\| \leqslant \frac{1}{A}\left(\left\|\left(I-Q_{I_{n}}\right) f\right\|+\frac{\varepsilon_{n}}{A-\varepsilon_{n}}\left\|Q_{I_{n}} f\right\|\right)$.

Proof. Note again that Lemma 3.4 guarantees that the choice of $M$ is possible. Now, for $g \in L^{2}(R)$ and natural numbers $M, m$, we have

$$
\begin{aligned}
& \sum_{(k, l) \notin I_{M+m}}\left|\left\langle g, f_{k, l}\right\rangle\right|^{2} \\
& \quad \leqslant \sum_{|k b| \geqslant M+m, l \in Z}\left|\left\langle g, f_{k, l}\right\rangle\right|^{2}+\sum_{||a| \geqslant M+m, k \in Z}\left|\left\langle g, f_{k, l}\right\rangle\right|^{2}=(*) .
\end{aligned}
$$

In order to estimate the first term in (*), write

$$
\left\langle g, f_{k, l}\right\rangle=\left\langle\left(I-Q_{M}\right) g, f_{k, l}\right\rangle+\left\langle Q_{M} g, f_{k, l}\right\rangle .
$$

Then

$$
\left|\left\langle g, f_{k, l}\right\rangle\right|^{2} \leqslant 2 \cdot\left|\left\langle\left(I-Q_{M}\right) g, f_{k, l}\right\rangle\right|^{2}+2 \cdot\left|\left\langle Q_{M} g, f_{k, l}\right\rangle\right|^{2} .
$$

By a similar estimate for the second term in (*), we get

$$
\begin{aligned}
(*) \leqslant & 2 \sum_{|k b| \geqslant M+m, l \in Z}\left|\left\langle\left(I-Q_{M}\right) g, f_{k, l}\right\rangle\right|^{2} \\
& +2 \sum_{|k b| \geqslant M+m, l \in Z}\left|\left\langle Q_{M} g, f_{k, l}\right\rangle\right|^{2} \\
& +2 \sum_{||a| \geqslant M+m, k \in Z}\left|\left\langle\left(I-R_{M}\right) g, f_{k, l}\right\rangle\right|^{2} \\
& +2 \sum_{||a| \geqslant M+m, k \in Z}\left|\left\langle R_{M} g, f_{k, l}\right\rangle\right|^{2} \\
\leqslant & 2 B\left(\left\|\left(I-Q_{M}\right) g\right\|^{2}+\left\|\left(I-R_{M}\right) g\right\|^{2}\right) \\
& +2 \sum_{|k b| \geqslant M+m, l \in Z}\left|\left\langle Q_{M} g, f_{k, l}\right\rangle\right|^{2} \\
& +2 \sum_{||a| \geqslant M+m, k \in Z}\left|\left\langle R_{M} g, f_{k, l}\right\rangle\right|^{2} \\
\leqslant & 2 B\left(\left\|\left(I-Q_{M}\right) g\right\|^{2}+\left\|\left(I-R_{M}\right) g\right\|^{2}\right) \\
& +(k(a, b)+k(b, a))\left(1+m^{2}\right)^{-2 \alpha+1}\|g\|^{2} .
\end{aligned}
$$

The choice of $M, m$ in the assumption now implies that

$$
\sum_{(k, l) \notin I_{M+m}}\left|\left\langle g, f_{k, l}\right\rangle\right|^{2} \leqslant \frac{\varepsilon_{n}^{2}}{B}\|g\|^{2}, \quad \forall g \in \mathscr{H}_{I_{n}} .
$$

This proves (i). (ii) is now a consequence of the version of Theorem 3.5 that we stated at the beginning of the section.
Q.E.D

A similar result for wavelets can be proved using the proof of [10, Theorem 3.2]. However, we will not encourage readers interesting in applications to do so! Instead we refer to the paper [7], where a different method to obtain the estimate (2) is used. In [7] it is proved that (2) is satisfied for a wavelet frame $\left\{D_{a^{k}} T_{l b} \phi\right\}$ if $J_{n}$ is chosen such that a finite number of conditions of the form " $\sum_{(k, l) \notin J_{n}}\left|\left\langle D_{a^{k}} T_{l b} \phi, \phi\right\rangle\right|^{2}$ small" is satisfied. This kind of condition is easy to satisfy because it only refer to the mother wavelet $\phi$.

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[^0]:    ${ }^{2}$ Note added in proof. Shortly before this paper was printed, the authors learned that the conjecture has been proved by P. Linnell. We refer to his paper Von Neumann algebras and linear independence of translates, Proc. Amer. Math. Soc. 127, No. 11 (1999), 3269-3277.

